Computational Finance, Fall 2016 Computer Lab 7

The aim of the Lab is to learn to use finite difference approximations of derivatives of a function and to derive finite difference methods for boundary value problems of ordinary differential equations.

Let us start from the numerical differentiation by finite difference approximations. Well-known finite difference approximations are as follows:

$$f'(x) \approx \frac{f(x+h) - f(x-h)}{2h} \quad (\text{error} \le ch^2),$$

$$f''(x) \approx \frac{f(x-h) - 2f(x) + f(x+h)}{h^2} \quad (\text{error} \le ch^2).$$

Exercise 1. Write a function myDerivative that takes four arguments - a name of a function, the value of x, the value of h and the order of the derivative (1 or 2) - and computes the value of the specified derivative at x using the finite difference approximation given above. Using this function, verify the accuracy of the error estimates in the case of several concrete functions and several values of x: compute the derivatives for $h = 1, \frac{1}{2}, \frac{1}{4}, \dots, \frac{1}{2^{10}}$ and find the quotient of the error to h^2 . The quotients should approach a constant value.

Finite difference approximations of derivatives can be used for deriving numerical methods for solving differential equations.

Let us consider the following problem: find y such that

$$y''(x) = f(x), x \in [a, b]$$
 (1)

$$y(a) = 1, \ y(b) = -1,$$
 (2)

where f is a given functions. The procedure for deriving a finite difference approximation for the problem above consists of the following steps.

- 1. Choose a set of points at which we want to find approximate values of the unknown function. Usually this set of points is chosen by dividing the interval [a, b] into n equal subintervals: we get points $x_i = a + ih$, $i = 0, \ldots, n$ where $h = \frac{b-a}{n}$.
- 2. In order to determine the approximate values of the solution y at the n+1 points, we need n+1 equations. We get those equations by using the boundary conditions (two equations) and by writing down the differential equation at a set of n-1 points \bar{x}_i , $i=1,\ldots,n-1$ and replacing the derivatives by approximations that use only the function values at points x_i , $i=0,\ldots,n$. The points \bar{x}_i , $i=1,\ldots,n-1$ do not have to be the same as the points x_i , $i=1,\ldots,n-1$, but in the case of the current problem let us use $\bar{x}_i=x_i$, $i=1,\ldots,n-1$.

If x_i , i = 0..., n are equally spaced (with stepsize $h = \frac{b-a}{n}$), then we can use the finite difference approximation discussed above:

$$y''(x_i) \approx \frac{y(x_{i-1}) - 2y(x_i) + y(x_{i+1})}{h^2}$$
 (error $\leq ch^2$).

Hence, writing out the differential equation at points x_i , i = 1, ..., n-1 and replacing derivatives with finite difference approximations we get a system of equations

$$\frac{y_{i-1}-2y_i+y_{i+1}}{h^2}=f(x_i),\ i=1,\ldots,n-1,$$

where y_i denotes the approximate values of $y(x_i)$. We can view the boundary conditions as two additional equations

$$y_0 = 1, \ y_n = -1.$$

Since *i*-th equation contains only 3 unknowns y_{i-1}, y_i, y_{i+1} the resulting matrix of the system of equations has non-zero entries only on three diagonals, so we obtain a three diagonal system of equations.

- Exercise 2. One possibility to solve a linear system of equations is to use the Python command linalg.solve(M,z) from the subpackage linalg of SciPy (that has to be imported first with from scipy import linalg), which returns the solution y of the system of equations My = z. Use this command to find the values of the approximate solution in the case n = 10, a = 0, b = 1, $f(x) = -24x^2$. Find the errors between the approximate solution and the exact solution $y(x) = 1 2x^4$.
- Exercise 3(*). If the system matrix has only some nonzero diagonals then it is actually a waste of computer memory to store the full matrix. For solving such system it is actually possible to use the command linalg.solve_banded((1,u),Dgs,z), where the rows of the matrix Dgs contain the diagonals of M starting from the highest one, l is the number of diagonals below the main diagonal and u is the number of diagonals above the main diagonal (in our case l=u=1).NB! In the matrix Dgs for the diagonals that are above the main diagonal the first elements are actually not used (for the diagonal directly above the main diagonal the first element is not used, for the next diagonal two steps above the main diagonal the first two elements are not used etc); for diagonals below the main diagonal last elements are not used. Write a function that for a given n solves the problem of the previous exercise with the command linalg.solve_banded((1,u),Dgs,z) and returns the maximal error at the points x_i , $i=1,\ldots,n-1$. Determine how many times the error is reduced if we increase the number of points two times.

Homework 3. (Deadline October 19, 2016) Consider the problem

$$(2+x)y''(x) + e^{0.1x}y'(x) - 3y(x) = 3, \ x \in [-1,3]$$
$$y'(-1) = 1, \ y(3) = -1.$$

Derive a finite difference approximation for the problem and write a function that for given n returns the values of the approximate solution at $x_i, i = 0, ..., n$, where x_i are equally spaced in the interval [-1,3]. Use approximations $y'(-1) \approx \frac{y(-1+h)-y(-1)}{h}$ for approximating the first boundary condition. Use your function to output the approximate values of $y(x_i)$, i = 0, ..., n for n = 20.